

Speaker: Jonatan Abraham (KTH Royal Institute of Technology, Sweden)

Presentation title: Using multiple data sources to produce an AI safety perception map of the city of Stockholm, Sweden

Co-authors: Vania Ceccato (KTH Royal Institute of Technology, Sweden) and Fabio Duarte (Massachusetts Institute of Technology, USA)

What does make a city (un)safe? Which are the most common urban features that make people declare feeling (un)safe? How do safety patterns relate to the physical and social landscape of urban environments according to different data sources? In this presentation, we present preliminary results of a research project that explores a combination of data sources to produce an AI safety perception map of the city of Stockholm, Sweden.